



Features

- On-Chip Hall Sensor
- 3.5V to 20V Supply Voltage
- 300mA (avg) Output Sink Current
- Reversed Supply Voltage Protection
- -20°C to 85°C Operating Temperature
- Low Profile TO-94 (SIP-4L) Package
- High ESD Performance

Applications

- Dual-Coil Brush-less DC Motor
- Dual-Coil Brush-less DC Fan
- Revolution counting
- Speed measurement

General Description

The TX3277 is an integrated Hall sensor with output driver designed for electronic commutation of brush-less DC motor applications. The device includes an on-chip Hall voltage, a Schmitt trigger to provide switching hysteresis for noise rejection, a temperature compensation circuit to compensate the temperature drift of Hall sensitivity and two complementary open-collector drivers for sinking large load current. It also includes an internal band-gap regulator which is

used to provide bias voltage for internal circuits. Placing the device in a variable magnetic field, if the magnetic flux density is larger than threshold BOP, the pin DO will be turned low (on) and pin DOB will be turned high (off). This output state is held until the magnetic flux density reverses and falls below BRP, then causes DO to be turned high (off) and DOB turned low (on). TX3277 is available in TO-94(SIP-4L) package.

Pin Assignment

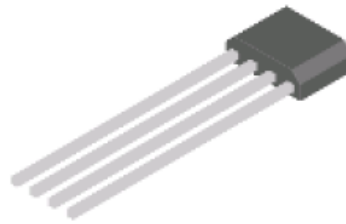


Fig 1

Pin Description

Pin Number	Pin Name	Function
1	Vcc	Supply voltage
2	DO	Output 1
3	DOB	Output 2
4	GND	Ground



Block Diagram

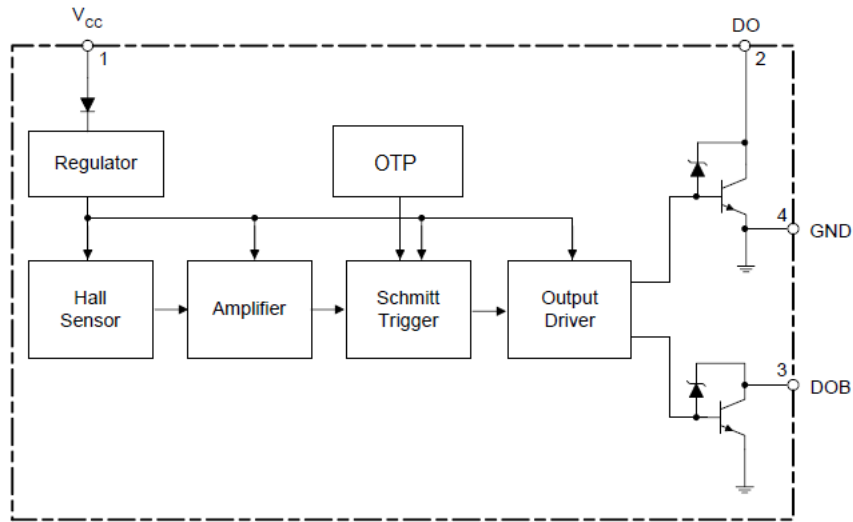


Fig 2

Absolute Maximum Ratings

Table1 (Ta=25°C)

Symbol	Parameter		Value	Unit
V _{CC}	Supply Voltage		20	V
V _{RCC}	Reverse Protection Voltage		-20	V
B	Magnetic Flux Density		Unlimited	Gauss
I _O	Output Current	Continuous	300	mA
		Hold	500	mA
		Peak(start up)	750	mA
PD	Power Dissipation		550	mW
θ _{JA}	Thermal Resistance	Die to atmosphere	227	°C/W
θ _{JC}		Die to package case	49	°C/W
TSTG	Storage Temperature		-50 to 150	°C

Note: Stresses greater than those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of these or any other conditions beyond those indicated under “Recommended Operating Conditions” is not implied. “Absolute Maximum Ratings” for extended period may affect device reliability.

**Recommended Operating Conditions**

Table 2 (Ta=25°C)

Parameter	Symbol	Min	Max	Unit
Supply Voltage	Vcc	3.5	20	V
Ambient Temperature	Ta	-20	85	°C

Electrical Characteristics

Table 3 (Vcc=12V, Ta=25°C, unless otherwise specified)

Symbol	Parameter	Test Conditions	Min.	Typ.	Max.	Unit
V _{SAT}	Output Saturation Voltage	V _{CC} =12V, I _o =100mA	-	0.1		V
		I _o =300mA		0.3	0.5	V
I _{OL}	Output Leakage Current	V _{CE} =16V	-	0.1	10	μA
I _{CC}	Supply Current	V _{CC} =12V, Output Open		12	16	mA
V _Z	Output Zener Breakdown Voltage			55		V
t _r	Output Rise Time	R _L =820 Ω C _L =20pF	-	3.0	10	us
t _f	Output Fall Time	R _L =820 Ω C _L =20pF	-	0.3	1.5	us
δ t	Switch Time Differential	R _L =820 Ω C _L =20pF	-	3.0	10	us

Magnetic Characteristics

Table 4 (Ta=25°C)

Characteristics	Symbol	Grade	Min	Typ	Max	Unit
Operating Point	B _{op}	A	20	35	50	Gauss
		B	10	-	70	Gauss
		C	-	-	90	Gauss
		D	-	-	125	Gauss
Releasing Point	B _{rp}	A	-50	-35	-20	Gauss
		B	-70	-	-10	Gauss
		C	-90	-	-	Gauss
		D	-125	-	-	Gauss
Hysteresis	B _{hys}	-	-	70	-	Gauss



Test Circuit

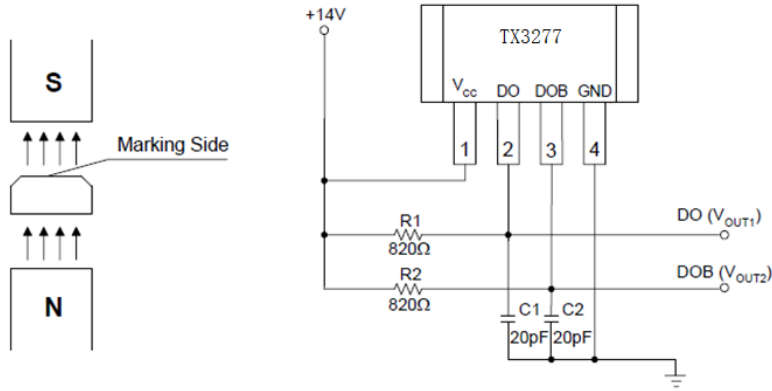


Fig 3 Test Circuit

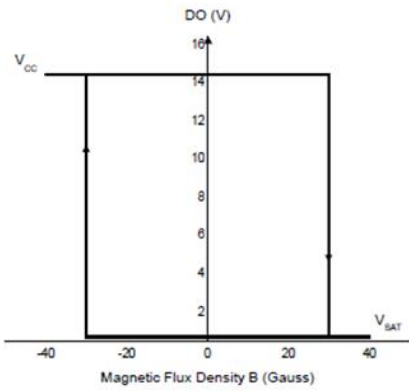


Fig 4 VDO vs. Magnetic Flux Density

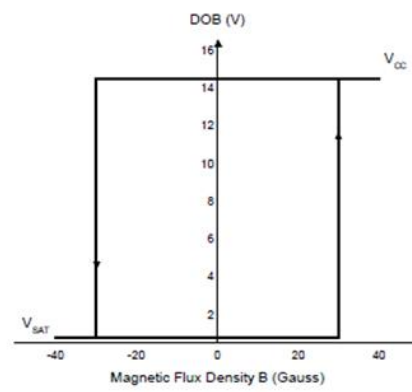


Fig 5 VDOB vs. Magnetic Flux Density

Application Circuits

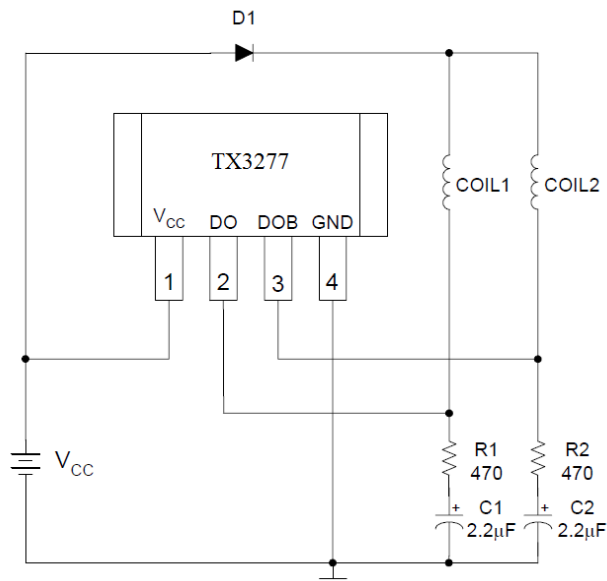


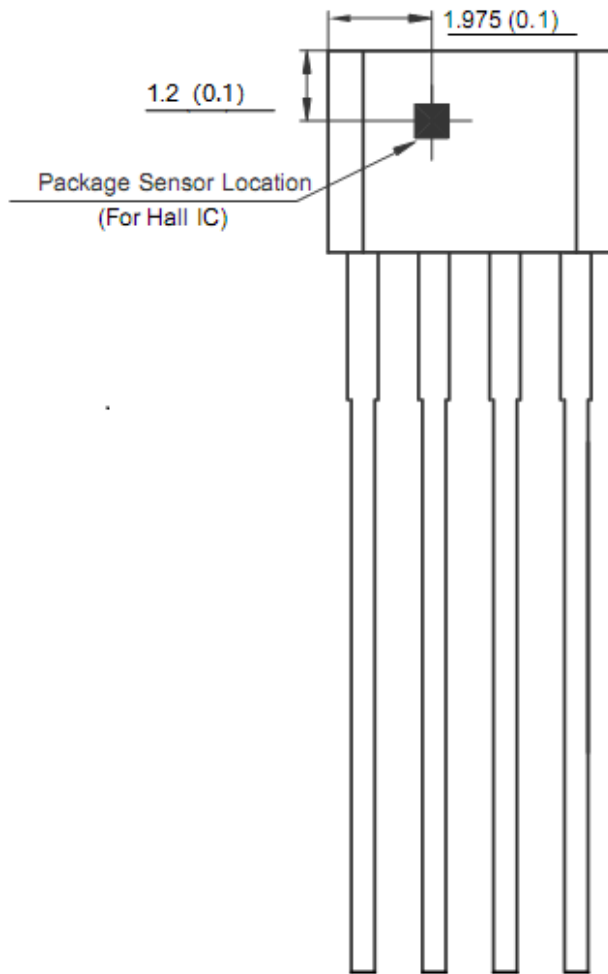


Fig 6

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Mechanical Dimensions



Unit:(mm)



Package Information

TO-94 PACKAGE OUTLINE DIMENSIONS

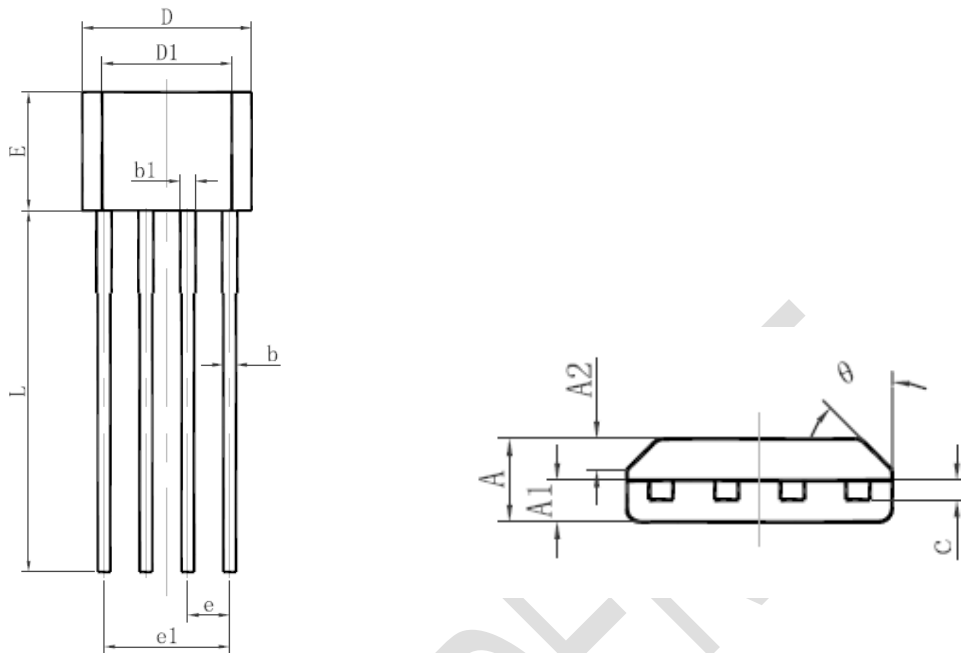


Fig 7

Symbol	Dimensions In Millimeters		Dimensions In Inches	
	Min.	Max.	Min.	Max.
A	1.400	1.800	0.055	0.071
A1	0.700	0.900	0.028	0.035
A2	0.500	0.700	0.020	0.028
b	0.360	0.500	0.014	0.020
b1	0.380	0.550	0.015	0.022
c	0.360	0.510	0.014	0.020
D	4.980	5.280	0.196	0.208
D1	3.780	4.080	0.149	0.161
E	3.450	3.750	0.136	0.148
e	1.270 TYP.		0.050 TYP.	
e1	3.710	3.910	0.146	0.154
L	14.900	15.300	0.587	0.602
θ	45° TYP.		45° TYP.	



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